

ABSTRACT OF THE DISCLOSURE

A method for delineating a frame. The method generally comprises the steps of (A) receiving the frame comprising (i) a length value incorporating a payload error detection length, (ii) a length error detection value, (iii) a payload data, and (iv) a payload error detection value having the payload error detection length, wherein the payload error detection value and the payload data occupy separate fields of the frame, (B) performing an error detection on the length value based upon the length error detection value, and (C) retrieving the payload data and the payload error detection value based upon the length value in response to passing the error detection on the length value.